



*Tough in Rough**



(*) Applications industrielles

Incremental encoder

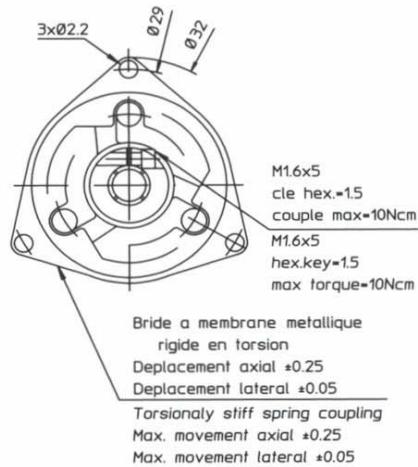
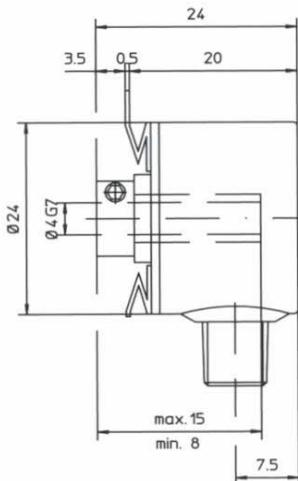
Designation	Val.
Counts per turn	I max. 3600
Switching frequency	f_{max} 25 kHz; optional 200 kHz
Speed	Max. $\leq 18000 \text{ min}^{-1}$
Logic level	HTL
Supply voltage	$\pm 10\%$ +5 V; +10...+30 V; +5 ...+24 V
Current consumption at no-load	35 mA
Average load current per channel	20 mA
Output amplitude	$U_{Low} \leq 0,375 \text{ V}$ $I_{OUT Low} = 10 \text{ mA}$
Moment of inertia	1 gcm ²
Driving torque at working temperature	0,1 Ncm
Load on shaft	Max. Axial: 20 N Radial: 20 N
Vibration proof	10 g / (10 – 2000 Hz)
Shock proof	100 g (11ms)
Temperature range (housing surface)	-40°C ... + 85°C
Protection degree	IP 64 IEC 34-5
Weight	0,125 kg

RADIO-ENERGIE TECHNOLOGY

Rev.: 01

General Characteristics:

- The most compact hollow shaft
- Easy mounting by flexible anti-rotation device
- Applications: micro-robotics, low power DC motors....



Blind hollow shaft, cable connection
Axe creux borgne, connexion par câble

Pulses per revolution /
Nombre d'impulsions par tour

1	60	250
4	75	256
11	80	300
12	90	360
15	100	400
25	125	500
30	128	1000*
50	150	1024*
56	180	2000*
	200	3000*
		3600*

(*) specify power supply / tension à préciser

5V
10 – 30

RCI 024 2RMHF XXXX X XX 64 XX X XXXX S

Type _____

Model _____

ppr _____

output signals

N = A + B + Z

I = A + B + Z

D = A + B + Z & A + B + Z

hollow shaft diameters

03 = Ø 3 mm

04 = Ø 4 mm

power supply

5 – 24 V

5 V

10 – 30 V

connection

S = cable, radial
B = cable, axial

cable length

01 = 1 m (standard)

XX = other

IP rating

64 = IP 64